#### Bayesian statistics and pomp

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#### Lecture outline

- 1. Motivating Bayesian statistics
- 2. Short introduction to Bayesian statistics and theory
- 3. Introduction to MCMC
- 4. Introduction to PMCMC
- 5. Simple influenza case study

What we have covered so far

 $p(y|\theta)$ 

 $\blacktriangleright$  y can be thought of as your data or observations  $\blacktriangleright$   $\theta$  can be thought of as the model or parameter values ▶ Called the "Likelihood"

#### Issues with maximum likelihood estimation (MLE)

- ▶ Assumes results occur with some given "frequency" over period time or replicates/repeated experiments
	- ▶ If we had the same outbreak hundreds of time, what proportion of them would provide confidence intervals that contain the true value for the  $R_0$
- ▶ Some difficulties in constraining parameter values based on outside data, information, or expert opinion
- $\blacktriangleright$  Just not really intuitive...
	- $\blacktriangleright$  We typically want to say something about the parameters based on the data,  $p(\theta|y)$

#### Bayesian statistics

- ▶ Bayes theorem provides an intuitive framework to update parameter estimates based on both prior knowledge and experimental data
- $\blacktriangleright$  End result is a posterior distribution,  $p(\theta | y)$ , directly describing the parameter and model of interest
- $\blacktriangleright$  Easy to communicate results
	- ▶ "The reproduction number is estimated to be x, with a 95% credible interval from y to z"
- ▶ Issues
	- $\blacktriangleright$  Computationally expensive
	- ▶ Without enough data, prior can bias posterior distribution, but this is what you want!

Bayes theorem 1

$$
p(\theta|y) = \frac{p(y|\theta)p(\theta)}{p(y)}
$$

 $\triangleright$   $p(\theta | y)$  is the posterior distribution  $\blacktriangleright$   $p(y|\theta)$  is the likelihood  $\blacktriangleright$   $p(\theta)$  is the prior distribution  $\blacktriangleright$   $p(y)$  is the marginal distribution (sometimes called a normalizing constant as it doesn't depend on the parameters) Bayes theorem 2

$$
p(\theta|y) = \frac{p(y|\theta)p(\theta)}{p(y)}
$$

 $\blacktriangleright p(y) = \int p(y|\theta)p(\theta)d\theta$ 

**• Probability of observing**  $y$  marginal over all possible values of  $\theta$ 

- ▶ Typically is very difficult to calculate
- $\blacktriangleright$  The good news is that  $p(y)$  is a constant

Bayes theorem 3

 $p(\theta|y) \propto p(y|\theta)p(\theta)$ 

- $\triangleright$  Since  $p(y)$  is a constant, the posterior distribution is proportional to the likelihood times the prior
- ▶ If we can solve this we can get the posterior distribution because  $\int p(\theta|y) d\theta = 1$
- ▶ Intuitively our parameter estimates are based on a combination of our observations  $p(y|\theta)$  and our prior beliefs  $p(\theta)$
- ▶ Only need to sample from the likelihood and prior distribution to get the posterior

#### How do we do so?

- ▶ Many ways to do so (and many software packages), but we're only going to talk about one…
- ▶ Markov chain Monte Carlo (MCMC) is a class of algorithms used to draw samples from a probability distribution
- ▶ Will not cover the theoretical details, but will attempt to motivate

Assume you have an unknown probability distribution (hill) to explore… How would you do so?

▶ You don't know where it is in parameter space

▶ You don't know it's shape

#### MCMC Robot Rules



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#### MCMC Robot Rules (actual) I



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#### MCMC Robot Rules (actual) II



Paul O. Lewis (2014 Woods Hole Molecular Evolution Workshop)

#### Drastic "off the cliff" Slightly downhill steps downhill steps are almost are usually accepted never accepted because because R is near 1  $8<sup>1</sup>$  $R$  is near  $0$ Currently at 6.2 m Proposed at 5.7 m  $6^{\circ}$ Currently at 6.2 m  $R = 5.7/6.2 = 0.92$ Proposed at 0.2 m  $R = 0.2/6.2 = 0.03$ 4† Currently at 1.0 m Proposed at 2.3 m  $R = 2.3/1.0 = 2.3$ 2 Uphill steps are 0 -The robot steps with always accepted because  $R > 1$ probability equal to R (or 1)

Paul O. Lewis (2014 Woods Hole Molecular Evolution Workshop)

## MCMC Robot Rules (actual) III

### MCMC Demonstration (https://plewis.github.io/applets/mcmc-robot/) I



#### MCMC Demonstration (https://plewis.github.io/applets/mcmc-robot/) II



#### MCMC Demonstration (https://plewis.github.io/applets/mcmc-robot/) III



#### MCMC Demonstration (https://plewis.github.io/applets/mcmc-robot/) IV



#### MCMC Demonstration (https://plewis.github.io/applets/mcmc-robot/) V



#### Steps for Metropolis-Hastings MCMC

- 1. Choose a reasonable starting place for parameters  $(\theta)$
- 2. Propose new parameter values  $(\theta')$
- 3. Calculate the proposal probability  $\alpha$
- 4. Accept (change parameters to  $\theta'$ ) or reject (keep parameters at  $\theta$ ) with probability  $\alpha$
- 5. Repeat steps 2-5 for as many MCMC iterations as desired

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Where

$$
\alpha = \min(1,\rho)
$$

and

$$
\rho = \frac{p(\theta'|y)}{p(\theta|y)} \cdot \frac{G(\theta|\theta')}{G(\theta'|\theta)}
$$

 $\rho$  equals the ratio of posterior distributions multiplied by the proposal probability ratio

$$
\rho = \frac{p(\theta^{'}|y)}{p(\theta|y)} \cdot \frac{G(\theta|\theta^{'})}{G(\theta^{'}|\theta)}
$$

▶ For symmetric proposal distributions (random walks)  $\frac{G(\theta|\theta')}{G(\theta'|\theta)}$  $\frac{G(\theta|\theta')}{G(\theta'|\theta)}=1$ Notice that the posterior denominators from before  $(p(y))$  cancel each other out in this ratio

We can simplify the acceptance probability significantly

$$
\rho = \frac{p(y|\boldsymbol{\theta}')p(\boldsymbol{\theta}')}{p(y|\boldsymbol{\theta})p(\boldsymbol{\theta})}
$$

▶ Only depends on the likelihood and prior probabilities

#### Prior parameter distributions

- ▶ Prior distributions assign probabilities to specific parameter values and are created separately for every parameter
- ▶ Other than strict constraints, we expect the data and likelihood to drive the posterior distribution, but always good idea to check the impact the prior distributions have in a sensitivity analysis

#### Three main types of prior distributions

- 1. Informative priors craft a distribution based on previous scientific studies
	- $\blacktriangleright$  Typically only used if a specific quantity is well known from outside data (e.g. the infection fatality rate or infectious period)
- 2. Weakly informative priors craft a distribution with reasonable constraints
	- ▶ Used for regularization (e.g. to "suggest" that a parameter is most likely to be positive)
- 3. Uninformative (flat priors) assign equal probabilities across a range of plausible values
	- ▶ Can constrain parameters to be strictly positive or in biologically/epidemiologically relevant range
	- ▶ Not always "uninformative"

Questions about MCMC?

#### PMCMC

# $p(y|\theta)p(\theta)$

▶ Standard MCMC algorithm assumes a deterministic likelihood

- ▶ When process stochasticisty is included we use the particle filter to obtain likelihood
- **Particle filter (Sequential Monte Carlo procedure) approximates**  $p(y|\theta)$ **, but** with variability
	- ▶ Can complicate things a bit, but usually not an issue

#### Further PMCMC resources

- $\blacktriangleright$  For an awesome field-specific explanation
	- ▶ Introduction to particle Markov-chain Monte Carlo for disease dynamics modellers
- ▶ For some considerations with modeling and inference
	- ▶ Choices and trade-offs in inference with infectious disease models
- ▶ For an example of how it has been used in recent epidemiological literature ▶ Estimating SARS-CoV-2 transmission parameters between coinciding outbreaks in a university population and the surrounding community
- ▶ For working with pmcmc in the pomp package
	- ▶ Getting started with pomp

Considerations for moving from mif2 to pmcmc in pomp

- 1. Specify the prior distributions for all parameters
- 2. Use the pmcmc() function
- 3. Use MCMC diagnostics to check convergence, etc.

#### Influenza boarding school example

▶ 1978 influenza epidemic in boarding school that infected much of the school ▶ Data are actually kids in beds, but we are assuming it's new infections



#### Modeling as an SIR model with reporting of new infections



Modeling as an SIR model with reporting of new infections

```
rproc <- Csnippet("
  double N = 2000;
  double t1 = \text{rbinom}(S.1-\exp(-\text{Beta*I/N*dt})):double t2 = \text{rbinom}(I, 1-\exp(-mu I*dt));S -= t1;
  I += t1 - t2;
  NI += t1;
  R += t2;
")
rmeas <- Csnippet("
  B = \text{rpois}(\text{rho*}NI+1e-6);
")
```
Specifying the prior distribution

```
priorDens <- Csnippet("
 lik = dunif (Beta, 1, 4, 1) +
        dunif(mu I, 0.5, 3, 1) +dunif(rho, 0.5, 1, 1);
 if (!give log) lik = exp(lik);
")
```
▶ Add the densities (probabilities) for each parameter value independently  $\blacktriangleright$  Include the same log functionality used before

▶ We are specifying a plausible range of values for each parameter here

#### Running an MCMC chain

flu |> *## Standard pomp object that has already been created* pomp(dprior = priorDens, *## Prior specified from previous slide* params = sim\_params, *## Parameter starting point* paramnames=c("Beta","mu\_I","rho")) |> *## Parameter names* pmcmc(Nmcmc = 10000, *## Number of MCMC iterations* Np = 200, *## Number of particles to use* proposal = mvn diag  $rw(rw.sd = c(Beta=0.3, mu I=0.3, rho=0.1))$ )  $\rightarrow$  test mcmc

#### Proposal distributions in pomp

- $\triangleright$  mvn diag rw(rw.sd) you provide the standard deviations for the proposals for each parameter
- $\triangleright$  mvn rw(rw.var) you provide the variance/covariance matrix for proposals
- $\triangleright$  mvn rw adaptive() you provide either of the above and it attempts to automatically "tune" parameters to achieve good MCMC mixing

#### Typically you need to test different values initially

flu |> *## Standard pomp object that has already been created* pomp(dprior = priorDens, *## Prior specified from previous slide* params = sim\_params, *## Parameter starting point* paramnames=c("Beta","mu\_I","rho")) |> *## Parameter names* pmcmc(Nmcmc = 10000, *## Number of MCMC iterations* Np = 200, *## Number of particles to use* proposal = mvn diag  $rw(rw.sd = c(Beta=0.3, mu I=0.3, rho=0.1))$ )  $\rightarrow$  test mcmc

#### Diagnosing chain mixing



#### Diagnosing chain mixing - autocorrelation

```
library(coda)
```

```
test mcmc |>
 traces() |>
  autocorr.diag(lags=c(10, 50, 100))
```
loglik log.prior Beta mu\_I rho Lag 10 0.8603731 NaN 0.8845398 0.8810328 0.8023407 Lag 50 0.5396487 NaN 0.5445343 0.5645781 0.3971658 Lag 100 0.3494610 NaN 0.3271410 0.3358897 0.2386606 mu\_R1 Lag 10 0.9990001 Lag 50 0.9950005 Lag 100 0.9900010

#### Second step often uses the empirical covariance matrix for proposals to improve mixing

```
flu |>
  pomp(dprior = priorDens,
       params = sim_params, ##Using the sim params as a starting spot
       paramnames=c("Beta","mu_I","rho")) |>
  pmcmc(Nmcmc = 10000,
        Np = 200,
        proposal = mvn_rw(covmat(test_mcmc, thin = 50))) \rightarrow test mcmc2
```
#### Improved trace plots!



#### Improved autocorrelation!

test\_mcmc2 |> traces() |> autocorr.diag(lags=c(10, 50, 100))



#### Estimating posterior distributions

- 1. Once you are happy with the mixing of your pmcmc you are ready to do a run for estimating posteriors
- 2. First randomly choose 3-5 starting parameter values (example uses Latin-hypercube sampling)
- 3. Run (in parallel or not depending on computational time) a chain intialized with each
- 4. Diagnose chain mixing with trace plots and Gelman-Rubin convergence diagnostic
- 5. Remove the burn-in period and thin based on diagnostics
- 6. Summarize parameter posterior distributions and credible intervals

#### Summary process for PMCMC in pomp

- 1. Create pomp object exactly as normal
- 2. Create the prior distributions for parameters
- 3. Run an initial pmcmc with mvn\_diag\_rw proposal to make sure it's working and diagnose
- 4. Randomly sample 3-5 parameter starting conditions
- 5. Run a PMCMC chain with mvn\_rw() proposal and the variance/covariance matrix from the first run for each of the initial parameter combinations
- 6. Diagnose mixing and convergence (alter components as needed)
- 7. Summarize parameters

Activity: how do stochastic and deterministic models differ?

- 1. Go to https://plewis.github.io/applets/mcmc-robot/, and play with different MCMC parameters and variations
- 2. Download the exercise code for the influenza boarding school example and test the impact of the following on mixing and traceplots:
	- ▶ Different parameters for the proposal distribution
	- ▶ Different starting parameter values
	- ▶ Different number of particles

#### License, acknowledgments, and links

- ▶ This lesson is prepared for the Simulation-based Inference for Epidemiological Dynamics module at the Summer Institute in Statistics and Modeling in Infectious Diseases, SISMID.
- ▶ The materials build on previous versions of this course and related courses.
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- ▶ Produced with R version 4.4.0 and pomp version 5.9.
- ▶ Compiled on 2024-07-24.

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R code for this lesson